

# Skimmer capacity for viscous oil spills

Accounting for viscous  
forces in skimmer design

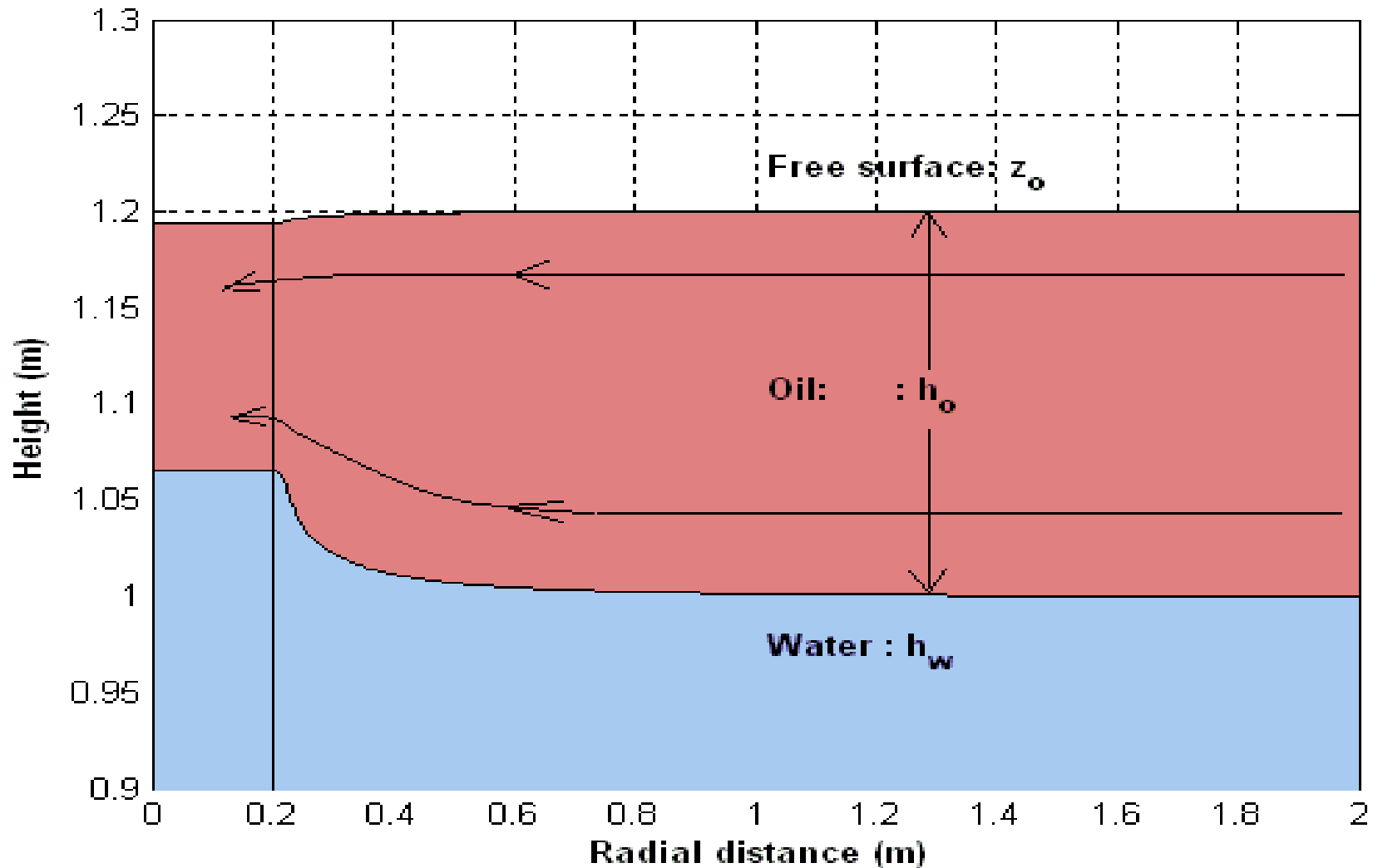
# Flow of floating, viscous oil towards a skimmer

Observed from above



# Flow of floating oil towards a skimmer

## x-section



# Skimmer design

## Traditional formulae

- Static, vertical equilibrium between oil and water
- Flow driven by height and density differences
- Flow opposed by inertia

# Sludge recovered from the EKOFISK tank in the North Sea

The fork will fall down, eventually



# Skimmer design

## Proposed model/formula

- Vertical equilibrium between oil and water
- Flow driven by height and density differences
- Flow opposed by inertia and viscous resistance

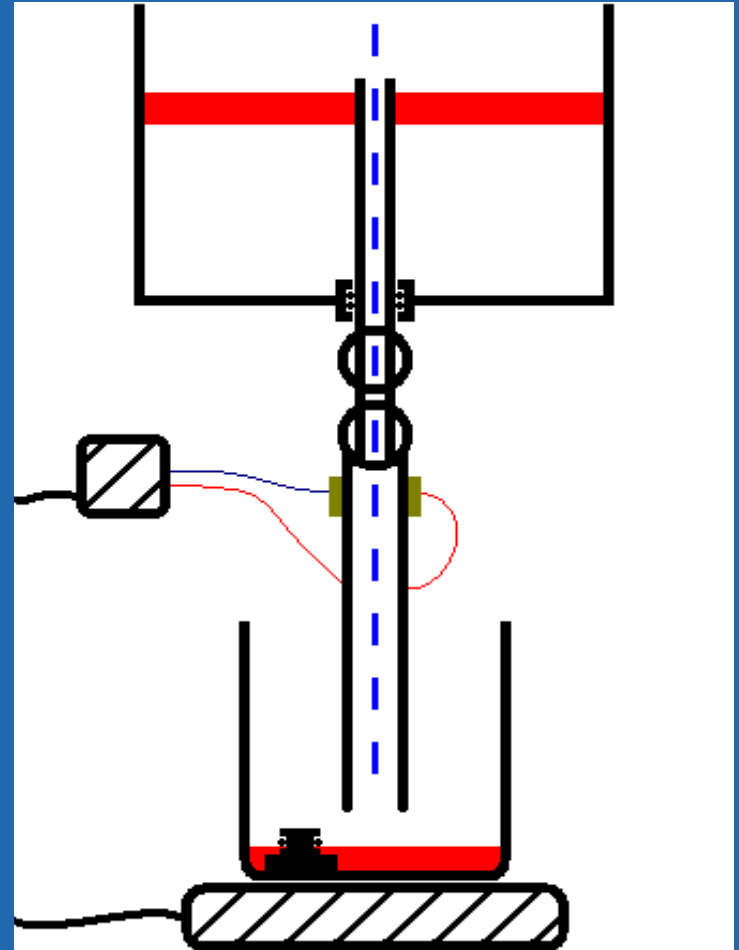
# Experimental facility

Water bucket, with observation window

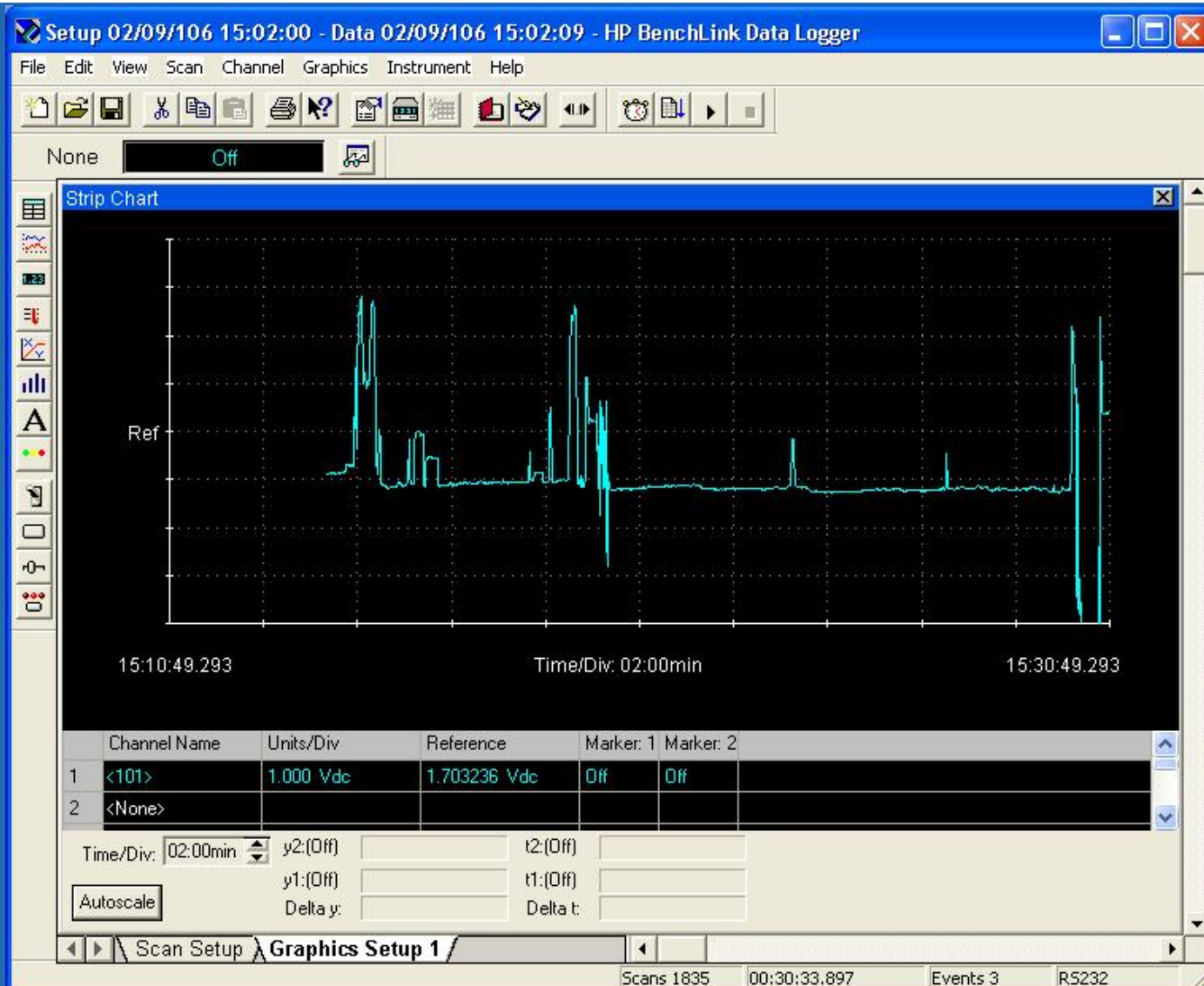


# Experimental facility

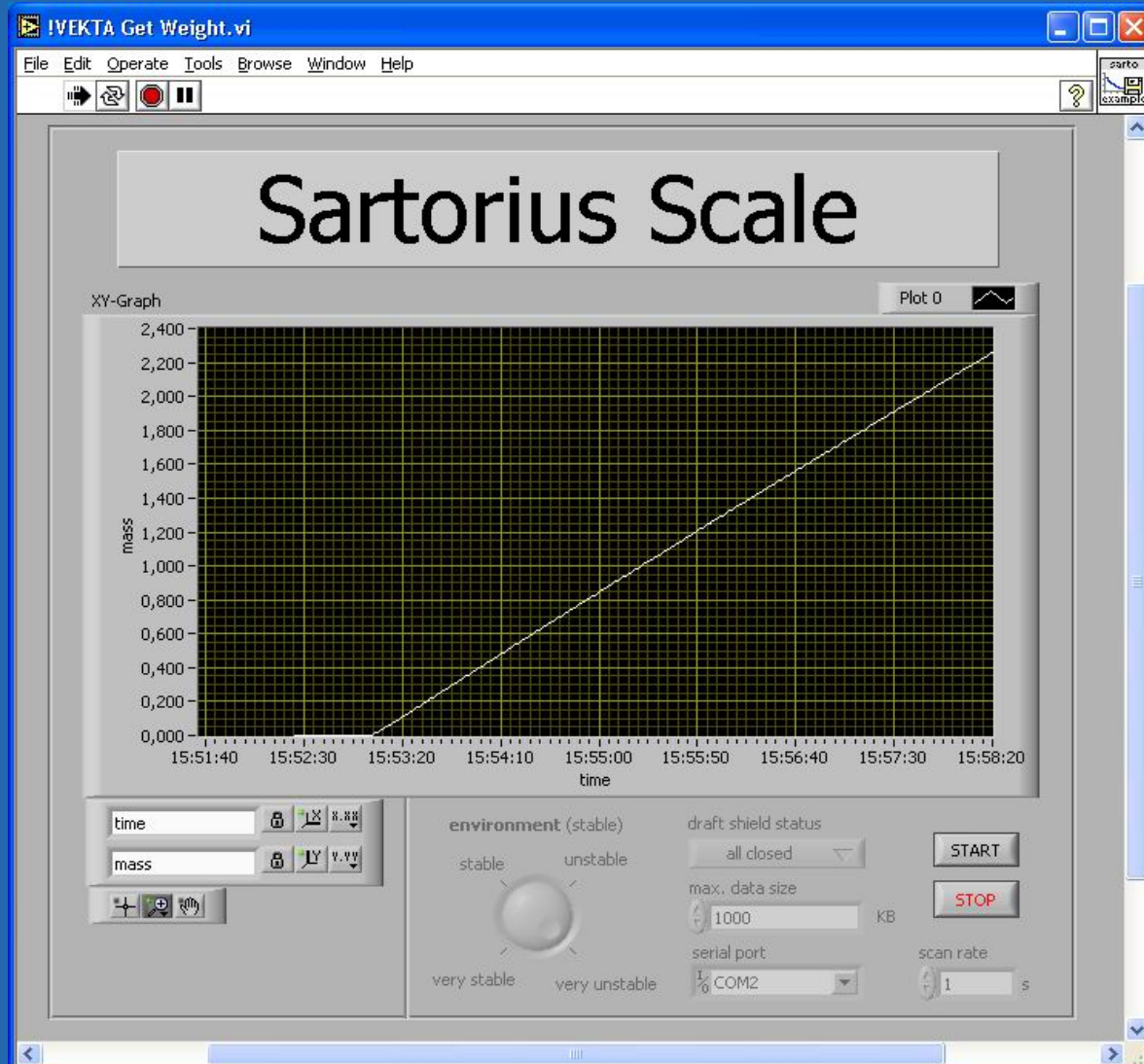
- Water tank, with floating oil
- Control valves
- Capacitance probe
- Outflow tank
- Electronic weight



# Capacitance of out flowing liquid



# Outflow rate measured by weight increase

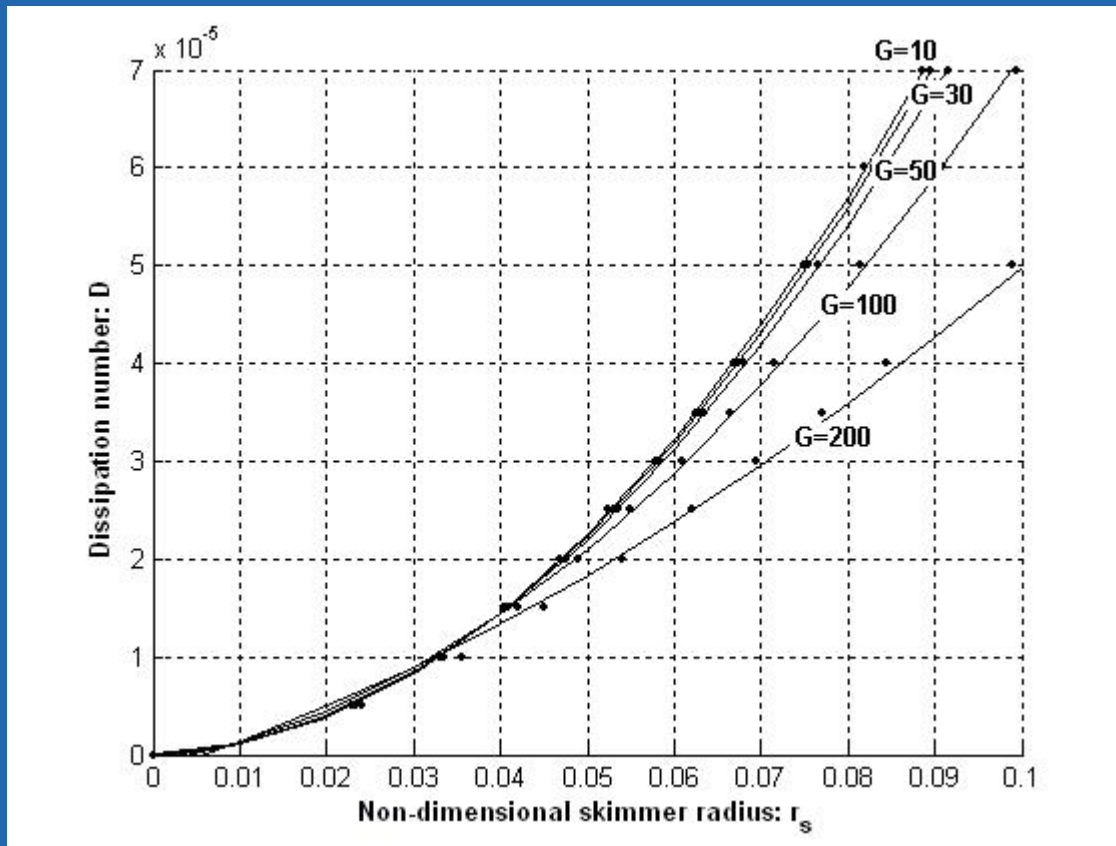


# Theoretical results

- Skimmer capacity is governed by 4 dimensionless parameters
- For all viscosities, skimmer performance may be predicted numerically by the method developed
- The effect of viscosity is not quantified by the viscosity itself, but by a dimensionless number, called the: Goose Number
- For Goose Numbers below 50, skimmer performance is governed by viscous forces (viscid regime). A design formula has been developed, by analytical approximation .
- For Goose Numbers above 2000, skimmer performance is governed by inertial forces (inviscid regime). Traditional skimmer capacity formula apply

# Viscid regime

## low Goose Numbers

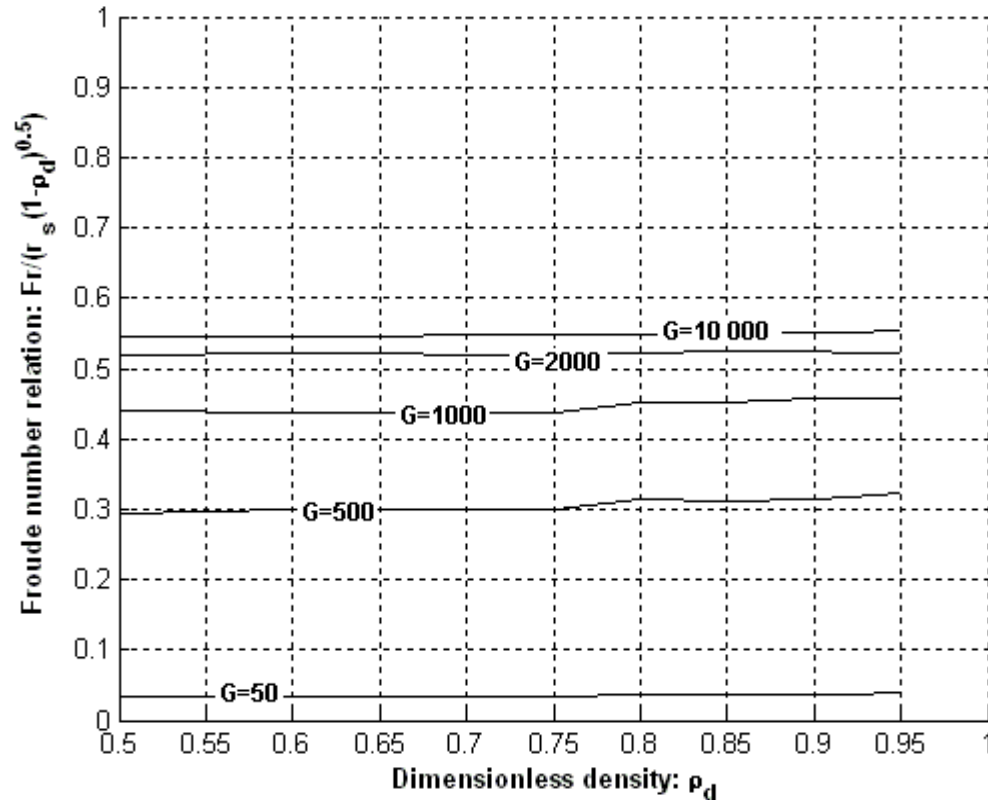


Skimmer design  
formula, for  $G < 50$

$$Q_o \approx \frac{\pi \rho_o g \tilde{r}_s^2 h_e^2}{\mu_o} \left( \frac{1 - \tilde{\rho}}{4 - \tilde{\rho}} \right)$$

# Inviscid regime

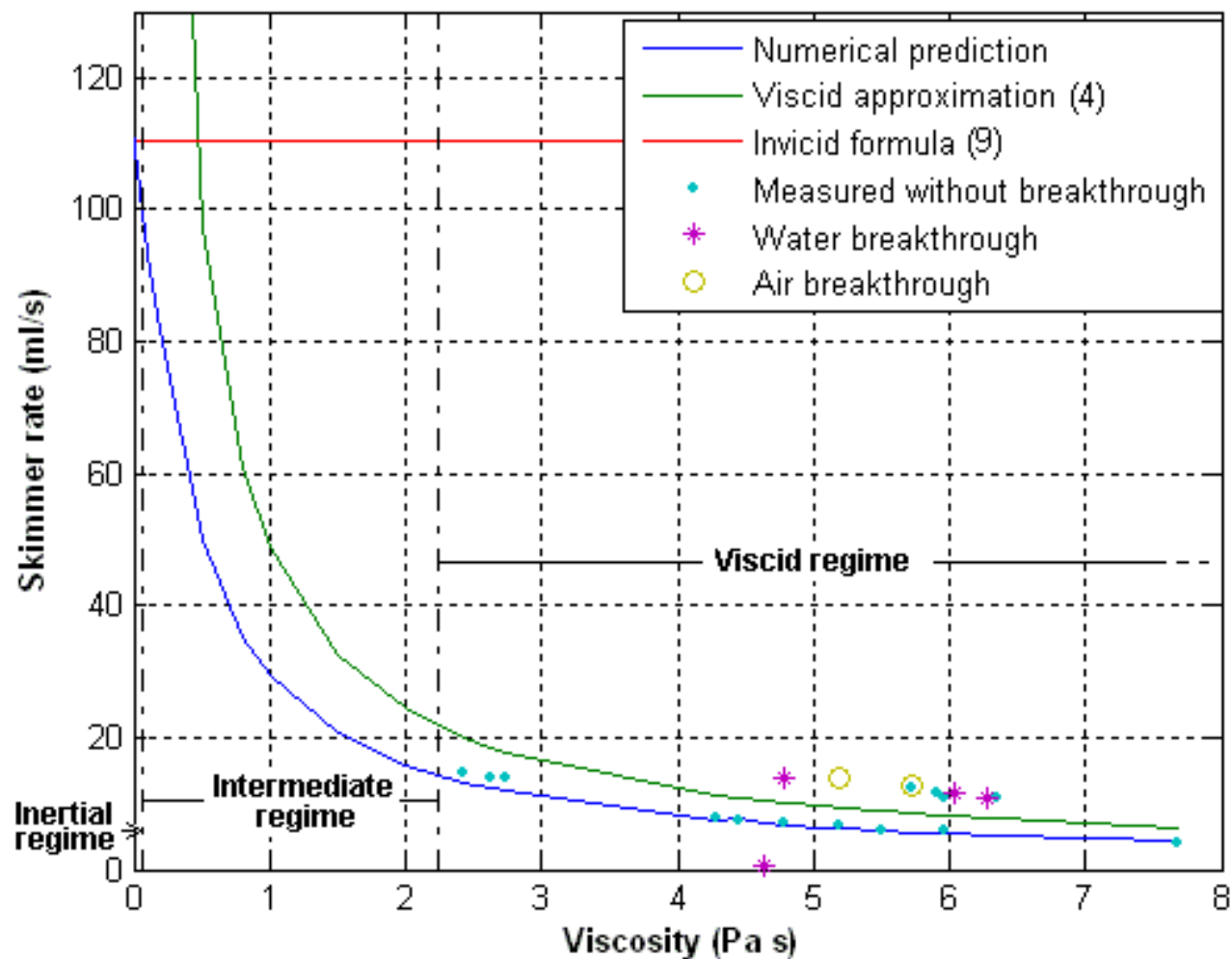
## High Goose Numbers



Skimmer design  
formula, for  $G > 2000$

$$Q_o = 2\pi r_s \sqrt{\left(\frac{2h_e}{3}\right)^3 (1-\tilde{\rho})g}$$

# Comparison of experiments and measurements



# Conclusions- round up

- Traditional skimmer design formulae apply to the inviscid regime (Goose Number $>2000$ ),
- A new design formula has been developed for the viscid regime (Goose Number $<50$ )
- Within the intermediate regime ( $50 < G < 2000$ ), neither viscous nor inertial forces should be neglected . No design formula presented. Skimmer performance may be predicted by numerical solution
- The experiments support the theoretical results
- The current results assume newtonian fluid behavior
- Performance prediction enables optimization of skimmer design and operation